

Overcoming Markowitz's instability with the help of the Hierarchical Risk Parity: theoretical evidence.

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- ▶ In this presentation we compare two methods of portfolio allocation: the classical Markowitz one [2] and the hierarchical risk parity (HRP) based on a clustered optimization [4]
- ▶ We derive theoretical values of a noise of the allocation weights coming from the covariance matrix numerical estimation.
- ▶ We demonstrate that the HRP is indeed less noisy (and thus more robust) w.r.t. the classical Markowitz
- ▶ We confirm the theory using Monte Carlo simulations
- ▶ We have derived the formulas for the min-variance optimization, Gaussian assets and low cross-correlations. However, our results can be generalized for other (analytical) portfolio optimization utility functions, arbitrary cross-correlations and potentially non-Gaussian processes.

- ▶ Our optimization universe contains different assets with prices $S_a(t)$ and weights $w_a(t)$ where a is assets index
- ▶ The portfolio return is a weighed sum of the asset *returns*, $\Delta X_a = \Delta S_a / S_a$, i.e.

$$\sum_a w_a(t) \Delta X_a(t)$$

- ▶ To calculate the weights on the next time period we proceed with minimizing/maximizing different utility functions of the distribution parameters of the portfolio increment: the simplest is the **min-var** optimization

Classical Markowitz

The min-var optimization is to find weights w which will minimize the portfolio variance subjected to one constraint, i.e. in vector/matrix notations:

$$\text{minimize } \sigma^2(w) = w^T V w \quad \text{s.t. } w^T a = 1$$

The assets *covariance matrix* V elements are often calculated as

$$V_{ab} = \frac{1}{T} \sum_{n=1}^{N_T} \Delta X_a(t_n) \Delta X_b(t_n)$$

where the summation run over (business-daily) tenor $\{t_n\}_{n=1}^{N_T}$, s.t. $t - T < t_1 < \dots < t_{N_T} < t$.

Using a constrained Lagrangian we obtain the following optimal weights and the optimal portfolio variance

$$w^* = \frac{V^{-1} a}{a^T V^{-1} a} \quad \text{and} \quad \sigma^2(w^*) = \frac{1}{a^T V^{-1} a}$$

Covariance matrix

To simplify the notations we scale the returns

$$X_{a,n} = \Delta X_a(t_n) / \sqrt{\Delta t_n}$$

to obtain

$$V_{ab} = \frac{1}{N_T} \sum_{n=1}^{N_T} X_{a,n} X_{b,n}$$

- ▶ Of course, the covariance matrix is not necessarily positively defined: either by nature (some assets are linearly dependent) or by calculation errors (MC estimation noise etc)
- ▶ However, there are multiple way to regularize it, e.g. using Pastur-Marchenko technique [1], Ledoit-Wolf [3] approach and others, see, for example, [5].
- ▶ The number of time-steps N_T and can be rarely above 1000 (4Y), otherwise, the estimated cov matrix will be "outdated".

MC noise for the Markowitz weights.

Let us proceed with our main goal: estimation of the "MC noise" coming from the covariance matrix summation

$$V_{ab} = \frac{1}{N_T} \sum_{n=1}^{N_T} X_{a,n} X_{b,n}$$

and penetrating into the optimal weights.

Let us decompose the estimated matrix in the exact value (denoted with "bar") and the finite-sample noise

$$V = \bar{V} + \Delta V$$

where the noise is Gaussian distribution for large N_T

$$\Delta V_{ab} = \frac{1}{N_T} \sum_p (X_{a,n} X_{b,n} - \mathbb{E}[X_a X_b])$$

Here X_a is a theoretical return stochastic variable.

Matrix expansion

Our first technique is based on the matrix expansion for small ΔV .

Example. Let us apply it to the noise of the inverse of the matrix

$$\Delta(V^{-1}) \equiv V^{-1} - \bar{V}^{-1}$$

Then, ignoring the square of ΔV in the following reasoning

$$(\bar{V}^{-1} + \Delta(V^{-1}))(\bar{V} + \Delta V) = 1 \Rightarrow \Delta(V^{-1})\bar{V} + \bar{V}^{-1}\Delta V = 0$$

we obtain the noise of the inverse covariance matrix

$$\Delta(V^{-1}) \approx -\bar{V}^{-1}\Delta V\bar{V}^{-1}$$

Comment. As we will see below, the answer for the low number of time-steps (say, corresponding to 1Y) can be sensitive to the second order of ΔV .

Inserting this approximation into the Markowitz formula we obtain¹

$$w \approx \frac{(\bar{V}^{-1} + \Delta(V^{-1})) a}{a^T (\bar{V}^{-1} + \Delta(V^{-1})) a}$$

Expanding it

$$w \approx \bar{w} + \Delta w$$

around the *exact weights*

$$\bar{w} = \frac{\bar{V}^{-1} a}{a^T \bar{V}^{-1} a}$$

we get the noise of the weights

$$\Delta w \approx -(1 - \bar{w} a^T) V^{-1} \Delta V \bar{w}$$

¹We have removed the star from the weights for brevity.

The noise expectation

We will measure the noise as a matrix expectation

$$\mathbb{E} \left[\Delta w \Delta w^T \right]$$

with elements $\mathbb{E} [\Delta w_a \Delta w_b]$. We calculate it as follows:

- ▶ The expectations depend on quadratic expression of ΔV
- ▶ It can be reduced to a 4-point expectations of X 's, i.e.
 $\mathbb{E} [X_n X_m X_i X_j]$
- ▶ We approximated them supposing that the normalized returns X are Gaussian.

Finally, we obtain a cute expression for the noise matrix

$$\mathbb{E} \left[\Delta w \Delta w^T \right] \approx \frac{1}{N_T} \left(\frac{\bar{V}^{-1}}{a^T \bar{V}^{-1} a} - \bar{w} \bar{w}^T \right)$$

The trace of the noise matrix $\mathbb{E} [\Delta w \Delta w^T]$ can be considered as a *one-number measure* of the Markowitz noise

$$\begin{aligned} \mathcal{N}_M &\equiv \mathbb{E} [\Delta w^T \Delta w] = \text{Tr} \left(\mathbb{E} [\Delta w \Delta w^T] \right) \\ &\approx \frac{1}{N_T} \left(\frac{\text{Tr} \bar{V}^{-1}}{a^T \bar{V}^{-1} a} - \frac{a^T \bar{V}^{-2} a}{(a^T \bar{V}^{-1} a)^2} \right) \end{aligned}$$

Comment. In practice we use the numerically calculated matrix V instead of its theoretical value \bar{V} in the final formula – this introduces an error of the order $O(N_T^{-2})$ which we can ignore.

To quantify the noise, we take an eigenvalues decomposition of the matrix \bar{V} (symmetric positive-definite after the regularization)

$$\bar{V} = U^T \Lambda U$$

where $U^T U = I$ and diagonal matrix Λ contains non-negative eigenvalues. We have

$$\text{Tr } \bar{V}^{-1} = \sum_q \lambda_q^{-1} \quad \text{and} \quad a^T \bar{V}^{-k} a = \sum_q b_q^2 \lambda_q^{-k}$$

where $b = U a$ and we sum over the assets $q = 1, \dots, N_A$.

$$\mathcal{N}_M \approx \frac{1}{N_T} \left(\frac{\sum_q \lambda_q^{-1}}{\sum_q b_q^2 \lambda_q^{-1}} - \frac{\sum_q b_q^2 \lambda_q^{-2}}{\left(\sum_q b_q^2 \lambda_q^{-1}\right)^2} \right)$$

One can easily prove that

$$\mathcal{N}_M \geq 0$$

for any b and λ .

We can consider two special cases:

- ▶ The inequality can become equality if one of eigenvalues λ_m^{-1} is dominant. In this case the noise is zero.
- ▶ In the opposite case, when the eigenvalues are all equal to each other the noise is maximum, i.e.

$$N_M = \frac{1}{N_T} \frac{N_A - 1}{\sum_q b_q^2}$$

where N_A is the number of assets.

If the portfolio is highly clustered one can come with the HRP optimization [4]. Below we will theoretically prove that it has a smaller MC noise.

Let us consider our assets (their returns) forming several *quasi-independent*, clusters or groups:

$$X = \{Y^{(1)}, \dots, Y^{(H)}\}$$

where H is the number of clusters.

Inside each group the correlation is close to one and intra-correlations are close to zero.

1. Calculate the Markowitz weights independently for all clusters

$$w^{(h)} = \frac{V^{(h)^{-1}} a^{(h)}}{a^{(h)T} V^{(h)^{-1}} a^{(h)}}$$

where the *cluster covariance matrix*

$$V_{ij}^{(h)} = \frac{1}{N_T} \sum_n Y_{i,n}^{(h)} Y_{j,n}^{(h)} \quad \text{and} \quad \bar{V}^{(h)} = \mathbb{E} \left[Y^{(h)} Y^{(h)T} \right]$$

and the corresponding vectors $a^{(h)}$ taken from the initial ones
 $a = (a^{(1)}, \dots, a^{(H)})$

2. Calculate a covariance matrix K (H by H) for *clustered* variables

$$C^{(h)} = w^{(h)T} Y^{(h)} \quad \text{for } h = 1, 2$$

defined as

$$K_{hq} = \frac{1}{N_T} \sum_{n,m,p} w_n^{(h)} Y_{n,p}^{(h)} Y_{m,p}^{(q)} w_m^{(q)}$$

It has simplified diagonal elements

$$K_{hh} = \Omega_h^{-1}$$

where we have denoted the quadratic form

$$\Omega_h = a^{(h)T} V^{(h)-1} a^{(h)}$$

The HRP procedure III

3. Calculate the final portfolio with weights ξ_h for the cluster variables

$$\Pi = \xi_1 C^{(1)} + \dots + \xi_H C^{(H)}$$

s.t. its variance

$$\sigma^2(\xi) = \mathbb{E}[\Pi] = \xi^T K \xi$$

is minimized provided that

$$\left(\xi_1 w^{(1)}, \dots, \xi_H w^{(H)} \right) \cdot \left(a^{(1)}, \dots, a^{(H)} \right) = 1$$

This is simply equivalent to

$$\xi_1 + \dots + \xi_H = \xi \cdot \iota = 1$$

where $\iota = (1, \dots, 1)$ because $w^{(h)} \cdot a^{(h)} = 1$.

The optimal values of the clusters weights are given by the Markowitz formula

$$\xi = \frac{K^{-1} \iota}{\iota^T K^{-1} \iota}$$

4. The final portfolio weights, $u^{(h)} = \xi_h w^{(h)}$, will be

$$\left(u^{(1)} \mid \dots \mid u^{(H)} \right) = \left(\xi_1 w_1^{(1)} \dots \xi_1 w_{N_1}^{(1)} \mid \dots \mid \xi_H w_1^{(H)}, \dots, \xi_H w_{N_H}^{(H)} \right)$$

The HRP noise

The total portfolio weights noise comes from:

- ▶ the cluster weights ξ
- ▶ the noise inside the clusters $w^{(h)}$

Summing them up we obtain the final HRP noise

$$\mathcal{N}_C = \frac{1}{N_T} \frac{1}{\Omega} \sum_h \left[\frac{a^{(h)T} V^{(h)-2} a^{(h)}}{\Omega_h} \left(1 - 2 \frac{\Omega_h}{\Omega} + 2 \frac{\Omega_h}{\Omega} \sum_r \frac{\Omega_r^2}{\Omega^2} \right) + \text{Tr} \bar{V}^{(h)-1} \frac{\Omega_h}{\Omega} \right]$$

where $\Omega = \sum_h \Omega_h$.

The HRP noise is less than the pure Markowitz noise: it is transparent esp. for a large number of clusters when $\Omega_h \ll \Omega$.

Below we confirm the theory with numerical experiments.

Numerical experiments

We set up a clustered correlation matrix with the following clusters on the block diagonal

cluster	0	1	2	3	4	5	6	7	8	9
sizes	10	17	5	17	7	9	15	9	11	3
corrs	0.9	0.8	0.8	0.9	0.8	0.8	0.7	0.8	0.7	0.7

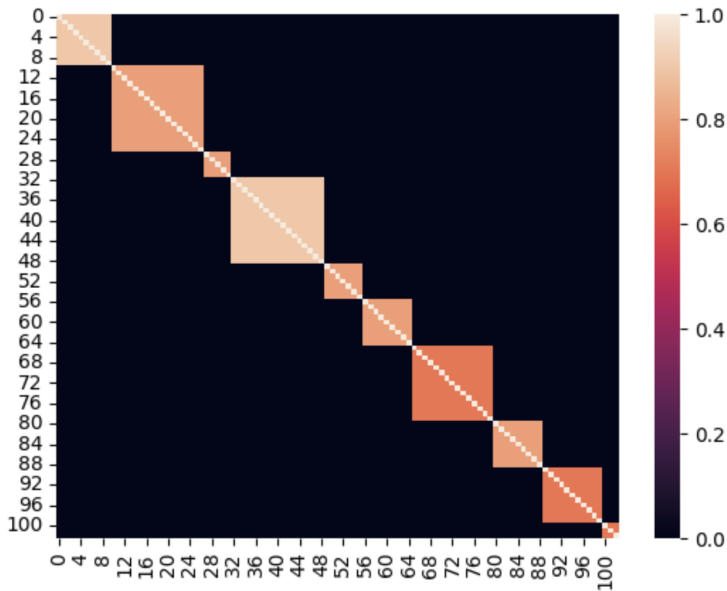
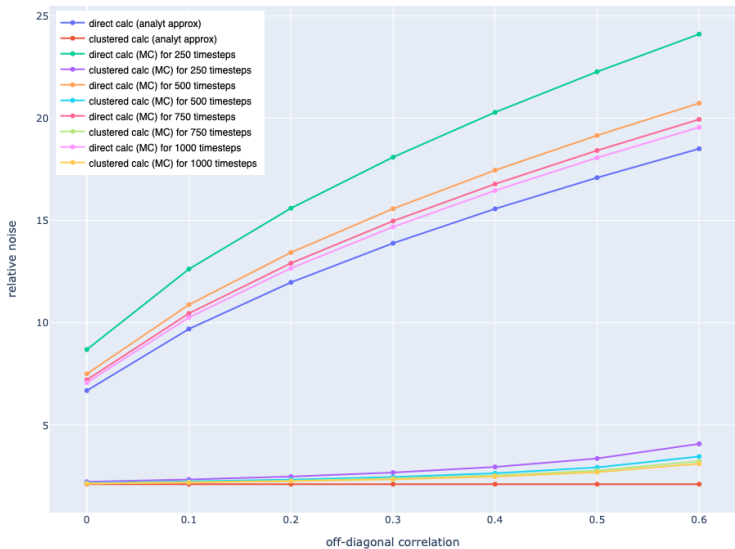


Figure: Clustered (block) correlation matrix.






- ▶ The number of assets corresponding to the matrix size is $N_A = 103$
- ▶ We perturb the initial correlation matrix with off-cluster values which we vary from 0 (unperturbed) till 0.6
- ▶ We simulate N_A Gaussians with these correlation matrices over variable number of time-steps N_T
- ▶ We try 250, 500, 750 and 1000 time-steps corresponding approximately to discretized 1Y, 2Y, 3Y and 4Y
- ▶ We produce sufficient number of samples for each trajectory – N_A assets over N_T time-steps – to ensure the Monte Carlo convergence
- ▶ We plot normalize noise $\sqrt{N_T E \Delta w^T \Delta w}$ for the direct Markowitz and $\sqrt{N_T \mathbb{E} [\Delta u^T \Delta u]}$ for the HRP



- ▶ A gap between MC noise calculation and the analytics for the Markowitz optimization is due to non-linear effects. Indeed, in the analytics we have ignored the second order of the covariance matrix noise. Increasing the number of time-steps reduces this gap
- ▶ A gap between the HRP MC noise calculation and the analytics is due to the non-linearity *and* the fact that the analytics ignores the off-diagonal elements
- ▶ The impact of the HRP to the noise reduction is significant: 3 times for a pure block structure and 5 for more significant off-diagonal correlations

- ▶ We calculated analytical formulas estimating the noise of portfolio optimization weights for both direct Markowitz optimization as well as the HRP one
- ▶ Their comparison shows that the HRP is less noisy than the direct Markowitz
- ▶ We have confirmed the analytical results by numerical experiments
- ▶ One can easily generalize the results for more complicated (but still analytical) portfolio optimizations

References

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